

## Mimetic Discrete Models with Weak Material Laws, or Least Squares Principles Revisited.

#### **Pavel Bochev**

Computational Mathematics and Algorithms
Sandia National Laboratories

Workshop on Compatible Discretizations, CAM, Oslo, 2005

Supported in part by







## Part I Mimetic Methods

- 1. What is a mimetic discretization
- 2. An algebraic topology framework
- 3. Direct and conforming discretizations

Mixed, Galerkin and Least-Squares methods for 2nd order problems share a common ancestor: the 4-field principle

A new interpretation of Least Squares: Realizations of a weak discrete Hodge \* operator

## A prelude: Least-Squares Principles

What are least-squares and the reasons to use them

LS acquire surprising new properties when elements from mixed methods are used

For diffusion problems they give

- the same scalar as Galerkin method
- the same flux as in the mixed method

#### Mac Hyman, Misha Shashkov

T-7
Los Alamos National Laboratory

## Part II Compatibility matters!

The Plan

Mimetic LSP for eddy currents and diffusion/heat equations and their advantages over nodal LS.

#### Max Gunzburger

**CSIT** 

Florida State University





## A Prelude





## **Least-squares 101**

$$\mathcal{L}u = f \text{ in } \Omega$$

$$\mathcal{R}u = h \text{ on } \Gamma$$

$$\min_{u \in X} J(u; f, h) = \frac{1}{2} \left( \left\| \mathcal{L}u - f \right\|_{X,\Omega}^{2} + \left\| \mathcal{R}u - h \right\|_{Y,\Gamma}^{2} \right)$$

$$\left( \mathcal{L}u, \mathcal{L}v \right)_{\Omega} + \left( \mathcal{R}u, \mathcal{R}v \right)_{\Gamma} = \left( f, \mathcal{L}u \right)_{\Omega} + \left( h, \mathcal{R}v \right)_{\Gamma}$$

$$\mathbf{A}\mathbf{u} = \mathbf{b}$$

#### Top 3 reasons people

#### want to do least squares:

- **<sup>☉</sup>** Using C<sup>0</sup> nodal elements
- Avoiding inf-sup conditions
- © Solving SPD systems

#### don't want to do least squares:

- **⊗** Conservation
- **⊗** Conservation
- **⊗** Conservation

#### We will show that:

- ➤ Using **nodal elements** is not necessarily the best choice in LSFEM, and so it is arguably the **least-important advantage** attributed to least-squares methods
- > By using other elements least-squares acquire additional conservation properties
- > Surprisingly, this kind of least-squares turns out to be **related** to **mixed methods**



Introduced by Jespersen (1977), Fix, Gunzburger and Nicolaides (1977-85). See also Cai, Carey, Chang, Jiang, Lazarov, Manteuffel et al. (1994-2000) and the survey B. & Gunzburger in SIAM Review, 1998

## Least-squares for diffusion



$$\nabla \cdot \mathbf{u} + \gamma \phi = f$$

$$\mathbf{u} + \nabla \phi = 0$$

$$\Leftrightarrow J(\mathbf{u}, \phi; f) = \frac{1}{2} (\|\nabla \cdot \mathbf{u} + \gamma \phi - f\|_{0}^{2} + \|\mathbf{u} + \nabla \phi\|_{0}^{2}) = 0$$



$$-\nabla \cdot \nabla \phi + \gamma \phi = f$$

$$-\nabla \cdot \nabla \phi + \gamma \phi = f \qquad \qquad \lim_{\mathbf{v} \in H_N(\Omega, div); \psi \in H_D^1(\Omega)} J(\mathbf{v}, \psi; f)$$

$$(\nabla \cdot \mathbf{u} + \gamma \phi, \nabla \cdot \mathbf{v}) + (\mathbf{u} + \nabla \phi, \mathbf{v}) = (f, \nabla \cdot \mathbf{v}) \quad \forall \mathbf{v} \in H_N(\Omega, \mathsf{div})$$

$$(\nabla \cdot \mathbf{u} + \gamma \phi, \gamma \psi) + (\mathbf{u} + \nabla \phi, \nabla \psi) = (f, \gamma \psi) \qquad \forall \psi \in H_D(\Omega, \mathsf{grad})$$

"Artificial" energy norm

 $J(\mathbf{u},\phi;0) = \frac{1}{2} \left( \left\| \nabla \cdot \mathbf{u} + \gamma \phi \right\|_{0}^{2} + \left\| \mathbf{u} + \nabla \phi \right\|_{0}^{2} \right) = \left\| \left( \mathbf{u},\phi \right) \right\|_{2}^{2}$ 

Norm equivalence

$$C_1(\|\mathbf{u}\|_{div}^2 + \|\phi\|_1^2) \le \|\|(\mathbf{u},\phi)\|\|^2 \le C_2(\|\mathbf{u}\|_{div}^2 + \|\phi\|_1^2)$$

Inner-product equivalence

$$Q_{LS}(\mathbf{u}, \phi; \mathbf{v}, \psi) = (\nabla \cdot \mathbf{u} + \gamma \phi, \nabla \cdot \mathbf{v} + \gamma \psi) + (\mathbf{u} + \nabla \phi, \mathbf{v} + \nabla \psi)$$

**Stability** 

$$C_1\left(\left\|\mathbf{u}\right\|_{div}^2 + \left\|\phi\right\|_1^2\right) \le Q_{LS}\left(\mathbf{u}, \phi; \mathbf{u}, \phi\right) \qquad \leftarrow \qquad \text{coercivity}$$

continuity 
$$\rightarrow Q_{LS}(\mathbf{u}, \phi; \mathbf{v}, \psi) \leq C_2 (\|\mathbf{u}\|_{div}^2 + \|\phi\|_1^2)^{1/2} (\|\mathbf{v}\|_{div}^2 + \|\psi\|_1^2)^{1/2}$$

# In the dark ages least-squares were deemed immune to compatibility

**Discrete equations** 

$$Q_{LS}(\mathbf{u}_h, \phi_h; \mathbf{v}_h, \psi_h) = (f, \nabla \cdot \mathbf{v}_h + \gamma \psi_h) \quad \forall (\mathbf{v}_h, \psi_h) \in \mathbf{V}_h \times S_h$$

Coercivity is inherited on all closed subspaces, and so any

$$\mathbf{V}_h \subset H(\Omega, div)$$
 &  $S_h \subset H^1(\Omega)$  (including  $\mathbb{C}^0$ )

are sufficient for stability of LSFEM and quasi-optimal energy norm error estimates

This was deemed to be a "get out of jail" card needed to throw away compatibility

⇒ all variables "can" be approximated by the same, equal order C<sup>0</sup> spaces

$$\underbrace{\left\|\mathbf{u} - \mathbf{u}_{h}\right\|_{div} + \left\|\phi - \phi_{h}\right\|_{1}}_{\text{energy norm}} \leq C \inf_{\left(\mathbf{v}_{h}, \psi_{h}\right) \in \mathbf{V}_{h} \times S_{h}} \left\|\mathbf{u} - \mathbf{v}_{h}\right\|_{div} + \left\|\phi - \phi_{h}\right\|_{1}$$

$$\left\|\phi - \phi_h\right\|_0 \le Ch \left\|\phi - \phi_h\right\|_1$$

← Using duality



## There was a little problem...

For LSP: conformity  $\Rightarrow$  stability but conformity  $\neq$  optimal L<sup>2</sup> accuracy!

 $\mathbf{V}_h \subset H(\Omega, div)$  &  $S_h \subset H^1(\Omega)$  is insufficient for optimal L<sup>2</sup> convergence of  $\mathbf{v}_h!$ 

LS vs BA	scalar		vector	
	L <sup>2</sup>	H¹	L <sup>2</sup>	H(div)
P1	2.00	1.00	1.38	0.99
ВА	2.00	1.00	2.00	1.00
P2	3.00	2.00	2.02	2.00
ВА	3.00	2.00	3.00	2.00

Optimal convergence of  $v_h$  in L<sup>2</sup> has been achieved in 2 ways





(Carey et al, Jiang, Manteuffel et al. 1994-1997)

## By using an augmented LS principle

Idea

$$\mathbf{u} + \nabla \phi = 0 \implies \nabla \times \mathbf{u} = 0$$

**Augmented PDE** 

$$\begin{cases}
\nabla \cdot \mathbf{u} + \gamma \phi = f \\
\mathbf{u} + \nabla \phi = 0
\end{cases} & & \nabla \times \mathbf{u} = 0 \text{ in } \Omega; \quad \phi = 0 \text{ on } \Gamma_D; \mathbf{u} \cdot \mathbf{n} = 0 \text{ on } \Gamma_N$$

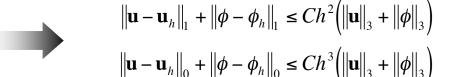
**Functional** 

$$J(\mathbf{u},\phi;f) = \frac{1}{2} \left( \left\| \nabla \cdot \mathbf{u} + \gamma \phi - f \right\|_{0}^{2} + \left\| \mathbf{u} + \nabla \phi \right\|_{0}^{2} + \left\| \nabla \times \mathbf{u} \right\|_{0}^{2} \right)$$

Norm equivalence

$$C_1(\|\mathbf{u}\|_1^2 + \|\phi\|_1^2) \le \|\mathbf{u}, \phi\|_1 \le C_2(\|\mathbf{u}\|_1^2 + \|\phi\|_1^2)$$

**Error estimate (P2)** 



#### The trouble with this approach

The range of the solution operator is restricted to a "smoother" space, causing the least-squares principle to miss less regular solutions that are admissible for the original PDE! We will see an example of this problem.





## Or, by using a special grid

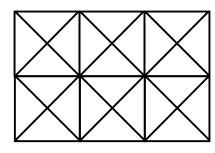
#### The Grid Decomposition Property (GDP)

$$\begin{cases} \mathbf{v}_{h} = \mathbf{w}_{h} + \mathbf{z}_{h} \\ \nabla \cdot \mathbf{z}_{h} = 0 \end{cases}$$

$$\forall \mathbf{v}_{h} \in V_{h}$$

$$\begin{cases} (\mathbf{w}_{h}, \mathbf{z}_{h}) = 0 \\ \|\mathbf{w}_{h}\|_{0} \leq C(\|\nabla \cdot \mathbf{v}_{h}\|_{-1} + h\|\nabla \cdot \mathbf{v}_{h}\|_{0}) \end{cases}$$

Fix. Gunzburger, Nicolaides, 1976



The (only known) Co example

#### **Theorem**

GDP is necessary and sufficient for stable and optimally accurate mixed discretization of the Least-Squares Principle (and the Mixed Method)

Fix, Gunzburger, Nicolaides, Comp. Math with Appl. 5, pp.87-98, 1979

Using the criss-cross grid and 
$$S_h = \nabla \cdot V_h$$
:



$$\|\mathbf{u} - \mathbf{u}_h\|_{div} + \|\phi - \phi_h\|_{1} \le Ch^{1}(\|\mathbf{u}\|_{2} + \|\phi\|_{2})$$

$$\|\mathbf{u} - \mathbf{u}_h\|_{0} + \|\phi - \phi_h\|_{0} \le Ch^{2}(\|\mathbf{u}\|_{2} + \|\phi\|_{2})$$



### The mixed Galerkin connection

#### Lemma

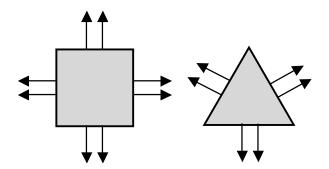
(Bochev, Gunzburger, SINUM 2005)

 $(V_h, S_h)$  satisfies the inf-sup condition  $\Rightarrow V_h$  verifies GDP

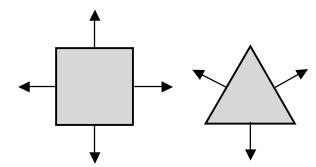
## There are plenty of spaces that verify GDP

Except that they are **not C**<sup>0</sup> (nodal)!

BDM(k) spaces k≥1



RT(k) spaces k≥0





## "Well-done" (mimetic) least-squares

Using nodal C<sup>0</sup> elements for all variables is not the best choice!

(despite of what some people tell you!)

Instead, pose the discrete LSP  $\min_{\mathbf{v}_h \in D^h; \psi_h \in G^h} J(\mathbf{v}_h, \psi_h; f)$  on this pair of spaces:

$$D^h \subset H_N(\Omega, \operatorname{div}) \longrightarrow \operatorname{any} \operatorname{with} \operatorname{GDP}$$

$$G^h \subset H^1_D(\Omega, \operatorname{grad}) \rightarrow \operatorname{any} \operatorname{that} \operatorname{is} C^0$$

Theorem. For proof see Bochev, Gunzburger, SIAM J. NUM. ANAL. 2005

For $\phi_h \in P_k$ and $\mathbf{u}_h \in BDM_k$ :	For $\phi_h \in P_k$ and $\mathbf{u}_h \in RT_k$ :
$\left\  \boldsymbol{\phi} - \boldsymbol{\phi}_h \right\ _0 + \left\  \mathbf{u} - \mathbf{u}_h \right\ _0 = O(h^{k+1})$	$\left\ \phi - \phi_h\right\ _0 + \left\ \mathbf{u} - \mathbf{u}_h\right\ _0 = O(h^k)$
$\left\  \boldsymbol{\phi} - \boldsymbol{\phi}_h \right\ _1 + \left\  \mathbf{u} - \mathbf{u}_h \right\ _{div} = O(h^k)$	$\left\  \boldsymbol{\phi} - \boldsymbol{\phi}_h \right\ _1 + \left\  \mathbf{u} - \mathbf{u}_h \right\ _{div} = O(h^k)$

Velocity and pressure spaces need not form a stable mixed pair!



#### **Theorem**

Assume that  $\left(\phi^{h},\mathbf{u}^{h}\right)$  solves the minimization problem

$$\min_{\boldsymbol{\phi}^h \in G^h : \mathbf{u}^h \in D^h} \tilde{K}(\boldsymbol{\phi}^h, \mathbf{u}^h) = \frac{1}{2} \left( \left\| \mathbf{A}^{-1/2} (\mathbf{u}^h + \mathbf{A} \nabla \boldsymbol{\phi}^h) \right\|_0^2 + \left\| \boldsymbol{\gamma}^{-1/2} (\nabla \cdot \mathbf{u}^h + \boldsymbol{\gamma} \boldsymbol{\phi}^h - f) \right\|_0^2 \right)$$

if  $\gamma>0$ ,  $\left(\phi^{h},\mathbf{u}^{h}\right)$  is **conservative** in the sense that there exists  $\mathbf{w}^{h}\in C^{h}$ ;  $\psi^{h}\in Q^{h}$  such that

$$\triangleright (\phi^h, \mathbf{w}^h) \in G^h \times C^h$$
 solves the Ritz-Galerkin method and  $\nabla \phi^h + \mathbf{w}^h = 0$ 

$$\blacktriangleright (\psi^h, \mathbf{u}^h) \in Q^h \times D^h$$
 solves the Mixed Galerkin method and  $\nabla \cdot \mathbf{u}^h + \gamma \psi^h = \Pi^h f$ 

In other words, the mimetic least-squares method computes

The same scalar approximation as in the Ritz-Galerkin method
The same vector approximation as in the Mixed Galerkin method



## Mimetic LS = Galerkin + Mixed Galerkin

error	grid	16	32	64	128
L2 u	Mimetic LS	0.1514803E+00	0.7192623E-01	0.3523105E-01	0.1745720E-01
LZ U	Mixed	0.1514803E+00	0.7192623E-01	0.3523105E-01	0.1745720E-01
H(dist)	Mimetic LS	0.2869324E+01	0.1397179E+01	0.6894290E+00	0.3426716E+00
H(div)	Mixed	0.2869324E+01	0.1397179E+01	0.6894290E+00	0.3426716E+00
L2 φ N	Galerkin	0.3997943E-02	0.9378368E-03	0.2274961E-03	0.5621838E-04
	Mimetic LS	0.3997943E-02	0.9378368E-03	0.2274961E-03	0.5621838E-04
	Mixed	0.3679584E-01	0.1778803E-01	0.8750616E-02	0.4340574E-02
H1 φ	Mimetic LS	0.2671283E+00	0.1296329E+00	0.6383042E-01	0.3166902E-01
	Galerkin	0.2671283E+00	0.1296329E+00	0.6383042E-01	0.3166902E-01

Scalar: L2 and H1 errors of Mimetic LS and Galerkin identical

**Vector:** L2 and H(div) errors of Mimetic LS and Mixed Galerkin identical





## A \$64K Question

### We see that a Least Squares perform better when using

nodal C<sup>0</sup> space for the scalar (same as in the Galerkin FEM)

- H(div) conforming space for the **vector** (same as in the **Mixed Galerkin** FEM)

## Q: what are the fundamental reasons for the method to acquire these new and attractive properties?

To answer this question we will use algebraic topology to develop a framework for compatible PDE discretizations. Then, we will examine different discrete models arising from this framework.





## Part 1





#### Algebraic topology provides the tools to mimic the PDE structure

- Computational grid is algebraic topological complex
- k-forms are encoded as k-cell quantities (k-cochains)
- Derivative is provided by the coboundary
- Inner product induces combinatorial Hodge theory
- Singular cohomology preserved by the complex

Framework for mimetic discretizations (Bochev, Hyman, IMA Proceedings)

Translation:
 Fields → forms → cochains

Basic mappings: reduction and reconstruction

Combinatorial operations: induced by reduction map

Natural operations: induced by reconstruction map

Derived operations: induced by natural operations

Branin (1966), Dodzuik (1976), Hyman & Scovel (1988-92), Nicolaides (1993), Dezin (1995), Shashkov (1990-), Mattiussi (1997), Schwalm (1999), Teixeira (2001), Marsden et al (DEC) and many others...





## **Differential Forms**

Smooth differential forms  $\Lambda^k(\Omega)$ :  $x \to \omega(x) \in \Lambda^k(T_x\Omega)$ 

**DeRham complex**  $\mathbf{R} \to \Lambda^0 \xrightarrow{d} \Lambda^1 \xrightarrow{d} \Lambda^2 \xrightarrow{d} \Lambda^3 \to 0$ 

Metric conjugation  $*: \Lambda^k(T_x\Omega) \to \Lambda^{n-k}(T_x\Omega) \Leftrightarrow \omega \wedge *\xi = (\omega,\xi)_x \omega_n$ 

L² inner product on  $\Lambda^k(\Omega)$   $(\omega,\xi)_{\Omega} = \int_{\Omega} (\omega,\xi)_{x} \omega_{n} \Rightarrow (\omega,\xi)_{\Omega} = \int_{\Omega} \omega \wedge *\xi$ 

Codifferential  $d^*: \Lambda^{k+1}(\Omega) \to \Lambda^{k+1}(\Omega) \Leftrightarrow (d\omega, \xi)_{\Omega} = (\omega, d^*\xi)_{\Omega}$ 

**Hodge Laplacian**  $\Delta : \Lambda^k(\Omega) \to \Lambda^k(\Omega)$   $\to \Delta = dd^* + d^*d$ 

Completion of  $\Lambda^k(\Omega)$   $\Lambda^k(L^2,\Omega)$ 

Sobolev spaces  $\Lambda^k (d,\Omega) = \left\{ \omega \in \Lambda^k (L^2,\Omega) \mid d\omega \in \Lambda^{k+1} (L^2,\Omega) \right\}$ 





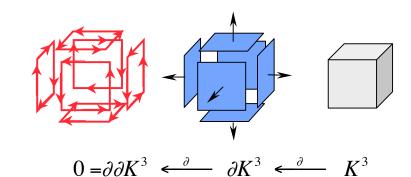
## Chains and cochains

### **Computational grid = Chain complex**

$$\partial: C_k \to C_{k-1}$$

$$\partial \partial = 0$$
  $C_0 \stackrel{\partial}{\longleftarrow} C_0$ 

$$\partial \partial = 0$$
  $C_0 \leftarrow \frac{\partial}{\partial C_1} \leftarrow \frac{\partial}{\partial C_2} \leftarrow \frac{\partial}{\partial C_3} \leftarrow C_3$ 



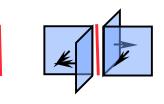
#### Field representation = Cochain complex

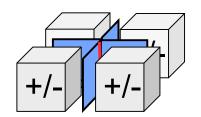
$$C^{k} = L(C_{k}, \mathbf{R}) = C_{k}^{*} \qquad \langle \sigma^{i}, \sigma_{j} \rangle = \delta_{ij}$$

$$\delta: C^k \to C^{k+1} \qquad \langle \omega, \partial \eta \rangle = \langle \delta \omega, \eta \rangle$$

$$\delta\delta = 0 \qquad C^0 \xrightarrow{\delta} C^1 \xrightarrow{\delta} C^2 \xrightarrow{\delta} C^3$$

$$K^1 \xrightarrow{\delta} \delta K^1 \xrightarrow{\delta} \delta \delta K^1 = 0$$









## **Basic mappings**

#### Reduction

$$\mathcal{R}: \Lambda^k(L^2,\Omega) \to C^k$$

#### **Natural choice**

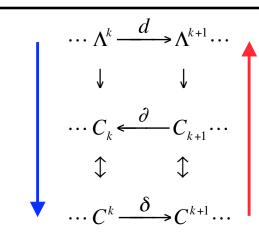
$$\langle \mathcal{R}\omega, \sigma \rangle = \int_{\sigma} \omega$$
DeRham map

$$\mathcal{R}d = \delta \mathcal{R}$$

#### **Proof**

$$\langle \delta \mathcal{R} \omega, c \rangle = \langle \mathcal{R} \omega, \partial c \rangle =$$

$$\int_{\partial c} \omega = \int_{c} d\omega = \langle \mathcal{R} d\omega, c \rangle$$



$$\Lambda^{k} \xrightarrow{d} \Lambda^{k+1} \qquad \Lambda^{k} \xrightarrow{d} \Lambda^{k+1}$$

$$\mathcal{R} \downarrow \text{CDPI} \downarrow \mathcal{R} \qquad \mathcal{I} \downarrow \text{CDP2} \downarrow \mathcal{I}$$

$$C^{k} \xrightarrow{\delta} C^{k+1} \qquad C^{k} \xrightarrow{\delta} C^{k+1}$$
natural required

## Range $\mathcal{IR} = \Lambda^k (L^2, K) \subset \Lambda^k (L^2, \Omega)$ Range $\mathcal{IR} = \Lambda^k (d, K) \subset \Lambda^k (d, \Omega)$

#### Reconstruction

$$\mathcal{I}:C^k\to\Lambda^k\big(L^2,\Omega\big)$$

#### No natural choice

$$\mathcal{RI} = id$$

$$\mathcal{IR} = id + O(h^s)$$

$$\ker \mathcal{I} = 0$$

#### **Conforming**

$$\mathcal{I}: C^k \to \Lambda^k (d, \Omega)$$

$$\mathcal{I}d = \delta \mathcal{I}$$





## **Combinatorial operations**

#### Discrete derivative

Forms are dual to manifolds

$$\langle d\omega, \Omega \rangle = \langle \omega, \partial \Omega \rangle$$

**Cochains** are dual to **chains** 

$$\langle \delta a, \sigma \rangle = \langle a, \partial \sigma \rangle$$

δ approximates d on cochains

#### Discrete integral

$$\int_{\sigma} a = \langle a, \sigma \rangle$$

#### Stokes theorem

$$\langle \delta a, \sigma \rangle = \langle a, \partial \sigma \rangle$$





## Natural and derived operations

**Natural** Inner product

$$(a,b)_x = (\mathcal{I}a,\mathcal{I}b)_x$$

$$(a,b)_x = (\mathcal{I}a,\mathcal{I}b)_x$$
  $(a,b)_\Omega = \int_\Omega (a,b)_x \omega_n = (\mathcal{I}a,\mathcal{I}b)_\Omega$ 

Wedge product

$$\wedge: C^k \times C^l \mapsto C^{k+l} \qquad a \wedge b = \mathcal{R}(\mathcal{I} a \wedge \mathcal{I} b)$$

$$a \wedge b = \mathcal{R}(\mathcal{I}a \wedge \mathcal{I}b)$$

**Derived** Adjoint derivative

$$\delta^*: C^{k+1} \mapsto C^k$$

$$\left(\delta^* a, b\right)_{\Omega} = \left(a, \delta b\right)_{\Omega}$$

Provides a second set of grad, div and curl operators. Scalars encoded as 0 or 3-forms, vectors as 1 or 2-forms, derivative choice depends on encoding.

Discrete Laplacian

$$D: C^k \mapsto C^k$$

$$D = \delta^* \delta + \delta \delta^*$$

Derived operations are necessary to avoid internal inconsistencies between the discrete operations: 1 is only approximate inverse of  $\mathcal R$  and natural operations will clash

Example Natural adjoint

$$d^* = (-1)^k * d *$$
 $\delta^* = (-1)^k \mathcal{R} * d * \mathcal{I}$ 

I must be regular and  $(\delta^* a, b)_{\Omega} = (a, \delta b)_{\Omega} + O(h^s) \Rightarrow \delta^*$  not true adjoint





## Mimetic properties (I)

**Discrete Poincare lemma** (existence of potentials in contractible domains)

$$d\omega_k = 0 \implies \omega_k = d\omega_{k+1}$$

$$\delta c^k = 0 \implies c^k = \delta c^{k+1}$$

**Discrete Stokes Theorem** 

$$\langle d\omega_{k-1}, c_k \rangle = \langle \omega_{k-1}, \partial c_k \rangle$$

$$\langle \delta c^{k-1}, c_k \rangle = \langle c^{k-1}, \partial c_k \rangle$$

**Discrete "Vector Calculus"** 

$$dd = 0$$

$$\delta\delta = \delta * \delta * = 0$$

$$\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$$

$$a \wedge b = (-1)^{kl} b \wedge a$$

$$d(\omega \wedge \eta) = d\omega \wedge \eta + (-1)^k \omega \wedge d\eta$$

$$\delta(a \wedge b) = \delta a \wedge b + (-1)^k a \wedge \delta b$$

(Regular 1)

Features of the continuum system that is implied by differential forms calculus is inherited by the discrete model

Called *mimetic* property by Hyman and Scovel (1988)





## Mimetic properties (II)

#### Inner product induces combinatorial Hodge theory on cochains

Co-cycles of 
$$(\Lambda^0, \Lambda^1, \Lambda^2, \Lambda^3)$$
  $\xrightarrow{\mathcal{R}}$  co-cycles of  $(C^0, C^1, C^2, C^3)$   $d\omega = 0$   $\Rightarrow$   $\delta \mathcal{R} \omega = 0$ 

#### **Discrete Harmonic forms**

$$H^{k}(\Omega) = \left\{ \eta \in \Lambda^{k}(\Omega) \mid d\eta = d^{*}\eta = 0 \right\}$$

$$H^{k}(K) = \left\{ c^{k} \in C^{k} \mid \delta c^{k} = \delta^{*}c^{k} = 0 \right\}$$

$$H^{k}(K) = \left\{ c^{k} \in C^{k} \mid \delta c^{k} = \delta^{*} c^{k} = 0 \right\}$$

#### **Discrete Hodge decomposition**

$$\omega = d\rho + \eta + d^*\sigma$$



#### **Theorem**

$$\dim \ker(\Delta) = \dim \ker(D)$$

Remarkable property of the mimetic *D* - kernel size is a **topological invariant!** 





## **Discrete \* operation**

#### **Natural definition** (Bossavit)

$$*_{N}: C^{k} \mapsto C^{n-k} \qquad *_{N} = \mathcal{R} * \mathcal{I}$$

$$*_{_{N}} = \mathcal{R} * \mathcal{I}$$

#### **Derived definition** (Hiptmair)

$$*_D: C^k \mapsto C^{n-k}$$

$$\int_{\Omega} a \wedge *_{D} b = (a,b)_{\Omega}$$

$$\int_{\Omega} a \wedge *_{D} b = (a,b)_{\Omega} \quad \text{mimics} \quad (\omega,\xi)_{\Omega} = \int_{\Omega} \omega \wedge *\xi$$

#### **Theorem**

$$*_{N}\mathcal{R}\omega^{h} = \mathcal{R}*\omega^{h} \quad \forall \omega^{h} \in \text{Range}(\mathcal{I}\mathcal{R})$$

CDP on the range

$$\int_{\Omega} \mathcal{I} \mathcal{R} \big( \mathcal{I} a \wedge \mathcal{I} *_{D} b \big) = \int_{\Omega} \big( \mathcal{I} a \wedge * \mathcal{I} b \big)$$

Weak CDP

$$\int_{\Omega} b \wedge *_{N} b = (a,b)_{\Omega} + O(h^{s})$$

$$*_N = *_D + O(h^s)$$



## The trouble with the discrete \*

Action of \* must be coordinated with the other discrete operations

	(•,•)	۸	$\delta^*$	Ŕ	1
*N	_			<b>✓</b>	
* <sub>D</sub>	1	<b>√</b>			_

Analytic \* is a local, invertible operation ⇒ positive diagonal matrix

$$\dim C^k \neq \dim C^{n-k} \implies *_N: C^k \mapsto C^{n-k}$$
 cannot be a square matrix!

Construction of \* is nontrivial task unless a primal-dual grid is used!





## **Implications**

A consistent discrete framework requires a choice of a primary operation either \* or (·,·) but not both

A discrete \* is the primary concept in Hiptmair (2000), Bossavit (1999)

- Inner product derived from discrete \*
- discrete \* used in explicit discretization of material laws

The **natural inner product** is the primary operation in our approach

- Sufficient to give rise to combinatorial Hodge theory on cochains
- Easier to define than a discrete \* operation
- Incorporate material laws in the natural inner product, or
- Enforce material laws weakly (justified by their approximate nature)





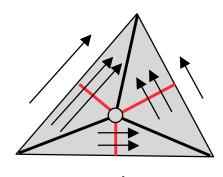
## Algebraic equivalents

Operation	Matrix form	type	
δ	$\mathbf{D}_{k}$	{-1,0,1}	
$(\cdot,\cdot)$	$\mathbf{M}_{k}$	SPD	
a <sub>1</sub> ∧b <sub>1</sub>	$\sum \mathbf{W}_{11}$	Skew symm.	
a₁∧b₂	$\sum \mathbf{W}_{12}$	$W_{12}^{T} = W_{21}$	
b <sub>2</sub> ∧a <sub>1</sub>	$\sum \mathbf{W}_{21}$		
δ*	$\mathbf{M}_{k}^{-1} \mathbf{D}_{k}^{T} \mathbf{M}_{k+1}$	rectangular	
Ф	$\mathbf{M}_{k}^{-1} \mathbf{D}_{k}^{T} \mathbf{M}_{k+1} \mathbf{D}_{k}^{T} + \mathbf{D}_{k-1} \mathbf{M}_{k-1}^{-1} \mathbf{D}_{k-1}^{T} \mathbf{M}_{k}$	square	
* <sub>D</sub>	$W_{12}(*_Da)=M_3a$	pair	



## Reconstruction and natural inner products

#### Co-volume



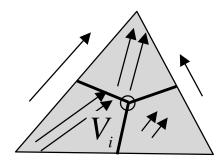
 $\mathcal{I}$ 

Nicolaides, Trapp (1992-04)

# $egin{pmatrix} h_1h_1^\perp & & & \ & h_2h_2^\perp & & \ & & h_3h_3^\perp \end{pmatrix}$

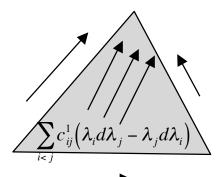
 $\delta^*$  local

#### **Mimetic**



Hyman, Shashkov, Steinberg (1985-04)

#### Whitney



Dodzuik (1976) Hyman, Scovel (1988)

$$\omega_{ij}^{1} = \lambda_{i} d\lambda_{j} - \lambda_{j} d\lambda_{i}$$

$$\ldots \qquad \ldots$$

$$\ldots \qquad (w, w, \lambda)$$

non-local

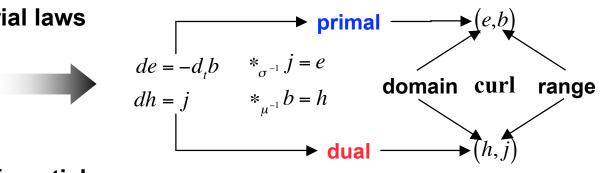


# Mimetic discretization of magnetic diffusion: translation to forms

#### 1st order PDE with material laws

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad \mathbf{J} = \sigma \mathbf{E}$$

$$\nabla \times \mathbf{H} = \mathbf{J} \quad \mathbf{B} = \mu \mathbf{H}$$

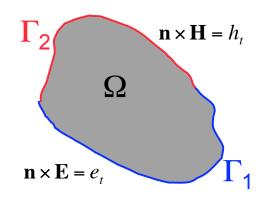


#### 1st order PDE with codifferentials

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$
$$\frac{1}{\sigma} \nabla \times \frac{1}{\mu} \mathbf{B} = \mathbf{E}$$

$$de = -d_t b$$

$$e = *_{\sigma^{-1}} d *_{\mu^{-1}} b$$



#### 2nd order PDE

$$\nabla \times \frac{1}{\sigma} \nabla \times \frac{1}{\mu} \mathbf{B} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$d *_{\sigma^{-1}} d *_{\mu^{-1}} b = -d_t b$$

NOTE: we could have eliminated the primal pair (E,B) and obtain the last two equations in terms of the dual pair (H,J).



# Option (I): Material properties via codifferentials

$$\delta \delta^* b^2 = -\delta_t b^2$$

$$e^1 \in C^1$$
;  $b^2 \in C^2$ 



$$\delta e^1 = -\delta_t b^2$$

$$e^1 = \delta^* b^2$$

$$d *_{\sigma^{-1}} d *_{u^{-1}} b = -d_t b$$

## Direct Conforming

$$de = -d_t b$$

$$e = *_{\sigma^{-1}} d *_{\mu^{-1}} b$$

$$\left(db_h^2, d\hat{b}_h^2\right)_{\Omega} = \left(-d_t b_h^2, \hat{b}_h^2\right)_{\Omega}$$

$$e_h^1 \in \Lambda^1(d,K); \quad b_h^2 \in \Lambda^2(d,K)$$

$$de_h^1 = -d_t b_h^2$$

$$\left(e_h^1, \hat{e}_h^1\right)_{\Omega} = \left(b_h^2, d\hat{e}_h^1\right)_{\Omega}$$

#### Theorem (Bochev & Hyman)

Assume that 1 is **conforming** reconstruction operator. Then, the **direct** and the **conforming** mimetic methods are completely equivalent.



## Option (II) Mimetic models with weak material laws

Translate 1st order system to an equivalent 4-field constrained optimization problem

$$de = -d_t b \quad *_{\sigma^{-1}} j = e$$

$$dh = j \quad *_{u^{-1}} b = h$$

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( *_{\sigma^{-1}} j - e \right) \right\|^2 + \left\| \sqrt{\mu} \left( *_{\mu^{-1}} b - h \right) \right\|^2 \right)$$
subject to  $de = -d_t b$  and  $dh = j$ 

#### Discretize in time

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( *_{\sigma^{-1}} j - e \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( *_{\mu^{-1}} b - h \right) \right\|^2 \right) \quad \text{subject to} \quad de = -\gamma \left( b - \overline{b} \right) \quad \text{and} \quad dh = j$$

#### Discretize in space (fully mimetic)

$$\begin{split} &\min\frac{1}{2}\Big(\Big\|\sqrt{\sigma}\big(\sigma^{-1}j_h^2-e_h^1\big)\Big\|^2+\Big\|\sqrt{\mu\gamma}\big(\mu^{-1}b_h^2-h_h^1\big)\Big\|^2\Big)\\ &\text{subject to}\quad de_h^1=-\gamma\big(b_h^2-\overline{b}_h^{\;2}\big) \text{ and } dh_h^1=j_h^2 \end{split}$$

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( \sigma^{-1} j^2 - e^1 \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( \mu^{-1} b^2 - h^1 \right) \right\|^2 \right)$$
 subject to  $\delta e^1 = -\gamma \left( b^2 - \overline{b}^2 \right)$  and  $\delta h^1 = j^2$ 

#### Conforming

**Direct** 

**Advantages** 



- Does not require a primal-dual grid complex
   Explicit discretization of material laws is avoided
   Construction of a discrete \* operation not required



# So, where are the least-squares? (An answer to the \$64K Question)

We start from the (fully) mimetic discrete 4-field principle

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( \sigma^{-1} j_h^2 - e_h^1 \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( \mu^{-1} b_h^2 - h_h^1 \right) \right\|^2 \right) \quad \text{subject to} \quad de_h^1 = -\gamma \left( b_h^2 - \overline{b}_h^2 \right) \quad \text{and} \quad dh_h^1 = j_h^2$$

But, instead of using Lagrange multipliers we note that constraints can be satisfied **exactly**.  $\Rightarrow$  we can **eliminate** the variables in the **ranges** of the differential operators:

$$de_{h}^{1} = -\gamma \left(b_{h}^{2} - \overline{b}_{h}^{2}\right) \implies b_{h}^{2} = \overline{b}_{h}^{2} - \gamma^{-1} de_{h}^{1} \implies \mu^{-1} b_{h}^{2} - h_{h}^{1} = \mu^{-1} \overline{b}_{h}^{2} - (\mu \gamma)^{-1} de_{h}^{1} - h_{h}^{1}$$

$$dh_{h}^{1} = j_{h}^{2} \implies j_{h}^{2} = dh_{h}^{1} \implies \sigma^{-1} j_{h}^{2} - e_{h}^{1} = \sigma^{-1} dh_{h}^{1} - e_{h}^{1}$$

The constrained 4 field principle reduces to the unconstrained (least-squares) problem

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( \sigma^{-1} dh_h^1 - e_h^1 \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( (\mu \gamma)^{-1} de_h^1 + h_h^1 - \mu^{-1} \overline{b}_h^2 \right) \right\|^2 \right)$$

⇒ a Mimetic LSP is equivalent to a fully compatible discretization of the 4-field principle

### Where are the mixed methods?

A fully mimetic discretization of the semidiscrete 4-field principle

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( *_{\sigma^{-1}} j - e \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( *_{\mu^{-1}} b - h \right) \right\|^2 \right) \quad \text{subject to} \quad de = -\gamma \left( b - \overline{b} \right) \quad \text{and} \quad dh = j$$

uses mimetic approximations for both the primal and the dual variables:

$$\Lambda^{1}(d,K) \times \Lambda^{2}(d,K) \Leftarrow \left(e_{h}^{1},b_{h}^{2}\right) \qquad \left((e,b);(h,j)\right) \qquad \left(h_{h}^{1},j_{h}^{2}\right) \Rightarrow \Lambda^{1}(d,K) \times \Lambda^{2}(d,K)$$

and **reduces to a mimetic least-squares**. However, we can apply mimetic discretization to just one of the two pairs of variables, either the primal or the dual:

$$\Lambda^{1}(d,K) \times \Lambda^{2}(d,K) \Leftarrow \left(e_{h}^{1},b_{h}^{2}\right) \qquad (e,b) \qquad \left(e_{h}^{2},b_{h}^{1}\right) \Rightarrow \Lambda^{2}(d,K) \times \Lambda^{1}(d,K)$$

$$\Lambda^{2}(d,K) \times \Lambda^{1}(d,K) \Leftarrow \left(h_{h}^{2},j_{h}^{1}\right) \qquad (h,j) \qquad \left(h_{h}^{1},j_{h}^{2}\right) \Rightarrow \Lambda^{1}(d,K) \times \Lambda^{2}(d,K)$$

A primal mimetic method

A dual mimetic method





## The primal mimetic method

We start from the primal mimetic discrete 4-field principle

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( \sigma^{-1} j_h^1 - e_h^1 \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( \mu^{-1} b_h^2 - h_h^2 \right) \right\|^2 \right) \quad \text{subject to} \quad de_h^1 = -\gamma \left( b_h^2 - \overline{b}_h^2 \right) \quad \text{and} \quad d^* h_h^2 = j_h^1$$

Clearly, the minimum is achieved when  $j_h^1 = \sigma e_h^1$  and  $h_h^2 = \mu^{-1} b_h^2$ . Instead of **eliminating** the constraints now we **eliminate** the functional and obtain the discrete system

$$de_h^1 = -\gamma (b_h^2 - \overline{b}_h^2)$$
 and  $d^* \mu^{-1} b_h^2 = \sigma e_h^1$ 

Using that  $\left(d^*h_h^2, \hat{e}_h^1\right) = \left(h_h^2, d\hat{e}_h^1\right) + \left\langle h_t, \hat{e}_h^1 \right\rangle_{\Gamma_2} \ \forall \ \hat{e}_h^1 \in \Lambda^1(d, K)$  gives the **mixed problem** 

$$de_h^1 = -\gamma \left(b_h^2 - \overline{b}_h^2\right) \quad \text{and} \quad \left(\mu^{-1}b_h^2, d\,\hat{e}_h^1\right) + \left\langle h_t, \hat{e}_h^1 \right\rangle_{\Gamma_1} = \left(\sigma e_h^1, \hat{e}_h^1\right) \quad \forall \,\, \hat{e}_h^1 \in \Lambda^1(d, K)$$

The range variable can be eliminated to obtain a Rayleigh-Ritz type equation

$$\gamma(\sigma e_h^1, \hat{e}_h^1) + (\mu^{-1} d e_h^1, d \hat{e}_h^1) = \gamma \langle h_t, \hat{e}_h^1 \rangle_{\Gamma_1} + \gamma (\mu^{-1} \overline{b}_h^2, d \hat{e}_h^1) \qquad \forall \hat{e}_h^1 \in \Lambda^1(d, K)$$

It is a fully discrete version of the equivalent, second order eddy current equation

$$\sigma \dot{\mathbf{E}} + \nabla \times \mu^{-1} \nabla \times \mathbf{E} = 0$$



## The three methods: summary

#### **Fully mimetic**

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( \sigma^{-1} j_h^2 - e_h^1 \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( \mu^{-1} b_h^2 - h_h^1 \right) \right\|^2 \right) \quad \text{subject to} \quad de_h^1 = -\gamma \left( b_h^2 - \overline{b}_h^2 \right) \quad \text{and} \quad dh_h^1 = j_h^2 \\ \min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( \sigma^{-1} dh_h^1 - e_h^1 \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( (\mu \gamma)^{-1} de_h^1 + h_h^1 - \mu^{-1} \overline{b}_h^2 \right) \right\|^2 \right)$$

#### **Primal** mimetic

$$\begin{split} \min \frac{1}{2} \Big( \Big\| \sqrt{\sigma} \big( \sigma^{-1} j_h^1 - e_h^1 \big) \Big\|^2 + \Big\| \sqrt{\mu \gamma} \big( \mu^{-1} b_h^2 - h_h^2 \big) \Big\|^2 \Big) \quad \text{subject to} \quad de_h^1 &= -\gamma \big( b_h^2 - \overline{b}_h^2 \big) \quad \text{and} \quad d^* h_h^2 = j_h^1 \\ de_h^1 &= -\gamma \big( b_h^2 - \overline{b}_h^2 \big) \quad \text{and} \quad \big( \mu^{-1} b_h^2, d\hat{e}_h^1 \big) + \left\langle h_t, \hat{e}_h^1 \right\rangle_{\Gamma_1} = \big( \sigma e_h^1, \hat{e}_h^1 \big) \quad \forall \; \hat{e}_h^1 \in \Lambda^1(d, K) \\ \gamma \big( \sigma e_h^1, \hat{e}_h^1 \big) + \big( \mu^{-1} de_h^1, d\hat{e}_h^1 \big) = \gamma \left\langle h_t, \hat{e}_h^1 \right\rangle_{\Gamma_1} + \gamma \big( \mu^{-1} \overline{b}_h^2, d\hat{e}_h^1 \big) \quad \forall \; \hat{e}_h^1 \in \Lambda^1(d, K) \\ \sigma \dot{\mathbf{E}} + \nabla \times \mu^{-1} \nabla \times \mathbf{E} = 0 \end{split}$$

#### **Dual mimetic**

$$\min \frac{1}{2} \left( \left\| \sqrt{\sigma} \left( \sigma^{-1} j_h^2 - e_h^2 \right) \right\|^2 + \left\| \sqrt{\mu \gamma} \left( \mu^{-1} b_h^1 - h_h^1 \right) \right\|^2 \right) \quad \text{subject to} \quad d^* e_h^2 = -\gamma \left( b_h^1 - \overline{b}_h^1 \right) \quad \text{and} \quad dh_h^1 = j_h^2$$
 
$$dh_h^1 = j_h^2 \quad \text{and} \quad \left( \sigma^{-1} j_h^2, d\hat{h}_h^1 \right) + \left\langle e_t, \hat{h}_h^1 \right\rangle_{\Gamma_2} = -\gamma \left( \mu h_h^1 + \overline{b}_h^1, \hat{h}_h^1 \right) \quad \forall \; \hat{h}_h^1 \in \Lambda^1(d, K)$$
 
$$\gamma \left( \mu h_h^1, \hat{h}_h^1 \right) + \left( \sigma^{-1} dh_h^1, d \; \hat{h}_h^1 \right) = -\left\langle e_t, \hat{h}_h^1 \right\rangle_{\Gamma_2} + \gamma \left( \overline{b}_h^1, \hat{h}_h^1 \right) \quad \forall \; \hat{h}_h^1 \in \Lambda^1(d, K)$$
 
$$\mu \dot{\mathbf{H}} + \nabla \times \sigma^{-1} \nabla \times \mathbf{H} = 0$$



## Mimetic LS = Primal + Dual Mimetic

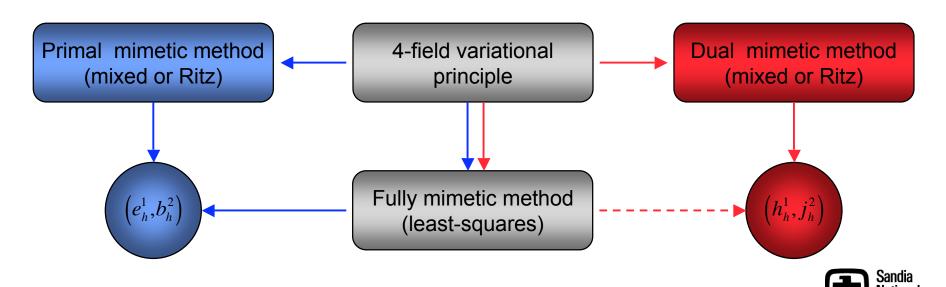
**Theorem** 

Let  $(e_h^1, b_h^2)$ ,  $(h_h^1, j_h^2)$  be the mimetic **least-squares** solution. Then  $(e_h^1, b_h^2)$  is the solution of the **primal** mimetic method

If b(x,0)=0, or we solve in frequency domain, we also have that

 $\left(h_h^1,j_h^2\right)$  is the solution of the dual mimetic method

This means, mimetic LS is equivalent to simultaneous solution of the primal and dual methods





#### **Proof**

The first order necessary condition for the least-squares principle is

$$\left(\sigma^{-1/2}dh_{h}^{1} - \sigma^{1/2}e_{h}^{1}, \sigma^{-1/2}d\hat{h}_{h}^{1} - \sigma^{1/2}\hat{e}_{h}^{1}\right) + \left((\mu\gamma)^{-1/2}de_{h}^{1} + (\mu\gamma)^{1/2}h_{h}^{1}, (\mu\gamma)^{-1/2}d\hat{e}_{h}^{1} + (\mu\gamma)^{1/2}\hat{h}_{h}^{1}\right) \\
= \left(\mu^{-1}(\mu\gamma)^{1/2}\overline{b}_{h}^{2}, (\mu\gamma)^{-1/2}d\hat{e}_{h}^{1} + (\mu\gamma)^{1/2}\hat{h}_{h}^{1}\right)$$

Expand each term

$$\left(\sigma^{-1/2}dh_{h}^{1} - \sigma^{1/2}e_{h}^{1}, \sigma^{-1/2}d\hat{h}_{h}^{1} - \sigma^{1/2}\hat{e}_{h}^{1}\right) = \left(\sigma e_{h}^{1}, \hat{e}_{h}^{1}\right) + \left(\sigma^{-1}dh_{h}^{1}, d\hat{h}_{h}^{1}\right) - \left(dh_{h}^{1}, \hat{e}_{h}^{1}\right) - \left(e_{h}^{1}, d\hat{h}_{h}^{1}\right)$$

$$\left((\mu\gamma)^{-1/2}de_{h}^{1} + (\mu\gamma)^{1/2}h_{h}^{1}, (\mu\gamma)^{-1/2}d\hat{e}_{h}^{1} + (\mu\gamma)^{1/2}\hat{h}_{h}^{1}\right) = \gamma\left(\mu h_{h}^{1}, \hat{h}_{h}^{1}\right) + \gamma^{-1}\left(\mu^{-1}de_{h}^{1}, d\hat{e}_{h}^{1}\right) + \left(de_{h}^{1}, \hat{h}_{h}^{1}\right) + \left(h_{h}^{1}, d\hat{e}_{h}^{1}\right)$$

The least-squares optimality system uncouples into two independent equations

$$\gamma\left(\sigma e_{h}^{1},\hat{e}_{h}^{1}\right)+\left(\mu^{-1}de_{h}^{1},d\hat{e}_{h}^{1}\right)=\gamma\left\langle h_{t},\hat{e}_{h}^{1}\right\rangle_{\Gamma_{2}}+\gamma\left(\mu^{-1}\overline{b}_{h}^{2},d\hat{e}_{h}^{1}\right)\quad\forall\hat{e}_{h}^{1}\in\Lambda^{1}(d,K)$$

$$\gamma\left(\mu h_{h}^{1},\hat{h}_{h}^{1}\right)+\left(\sigma^{-1}dh_{h}^{1},d\hat{h}_{h}^{1}\right)=-\left\langle e_{t},\hat{h}_{h}^{1}\right\rangle_{\Gamma_{1}}+\frac{\gamma\left(\overline{b}_{h}^{2},\hat{h}_{h}^{1}\right)}{\gamma\left(\overline{b}_{h}^{2},\hat{h}_{h}^{1}\right)}\quad\forall\hat{h}_{h}^{1}\in\Lambda^{1}(d,K)$$
Primal mimetic

If b(x,0)=0, or in frequency domain, then the 2nd LS equation is identical to

$$\gamma\left(\mu h_h^1, \hat{h}_h^1\right) + \left(\sigma^{-1}dh_h^1, d\hat{h}_h^1\right) = -\left\langle e_t, \hat{h}_h^1 \right\rangle_{\Gamma 1} + \gamma\left(\overline{b}_h^1, \hat{h}_h^1\right) \qquad \forall \hat{h}_h^1 \in \Lambda^1(d, K) \qquad \qquad \text{Dual mimetic}$$





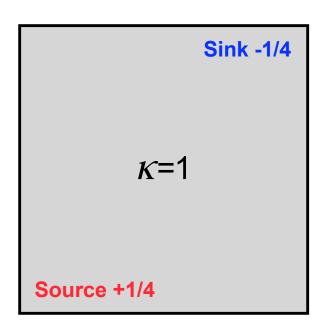
Part II
(the fun part)

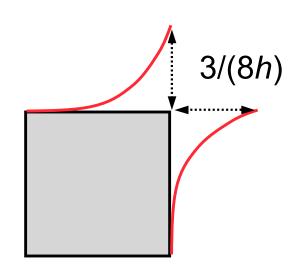




## **Diffusion: The 5 Spot Problem**

From: T. Hughes, A. Masud and J. Wan, A stabilized mixed DG method for Darcy flow



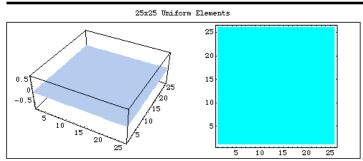


- > Problem is driven by a Neumann boundary condition (normal flux)
- ➤ Source/Sink is approximated by an equivalent distribution of the normal flux
- > Solved as a time-dependent problem (heat equation) using Implicit Euler
- ➤ Grid has 625 uniform quad elements





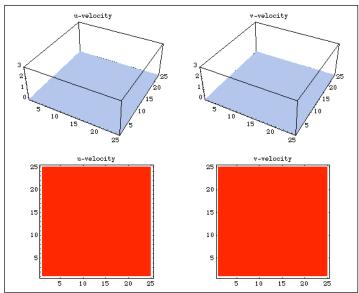
#### **No Source Term**



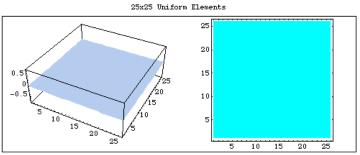
Mimetic LS Pressure dt=0.01, nt=100

#### mimetic

25x25 Uniform Elements



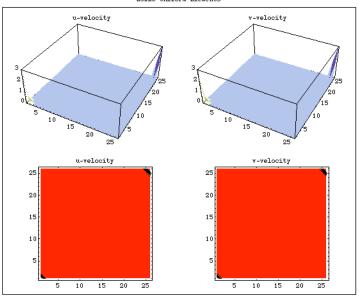
Mimetic LS Velocity. dt=0.01, nt=100



Q1-Q1 LS Pressure dt=0.01, nt=100

#### nodal

25x25 Uniform Elements

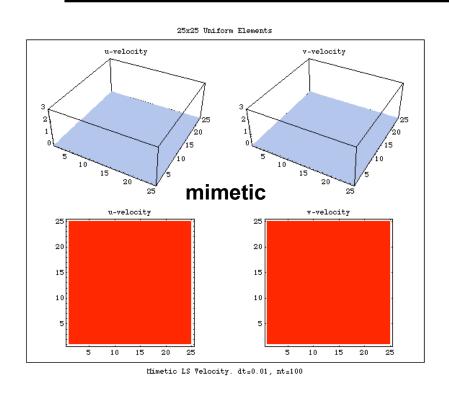


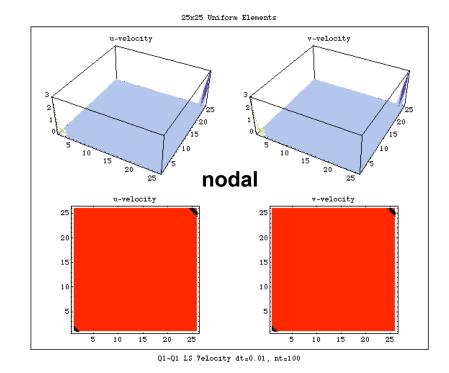
Q1-Q1 LS Velocity  $\mathtt{dt}_{=}0.01\text{, }\mathtt{nt}_{=}100$ 





### **Oscillatory Source**





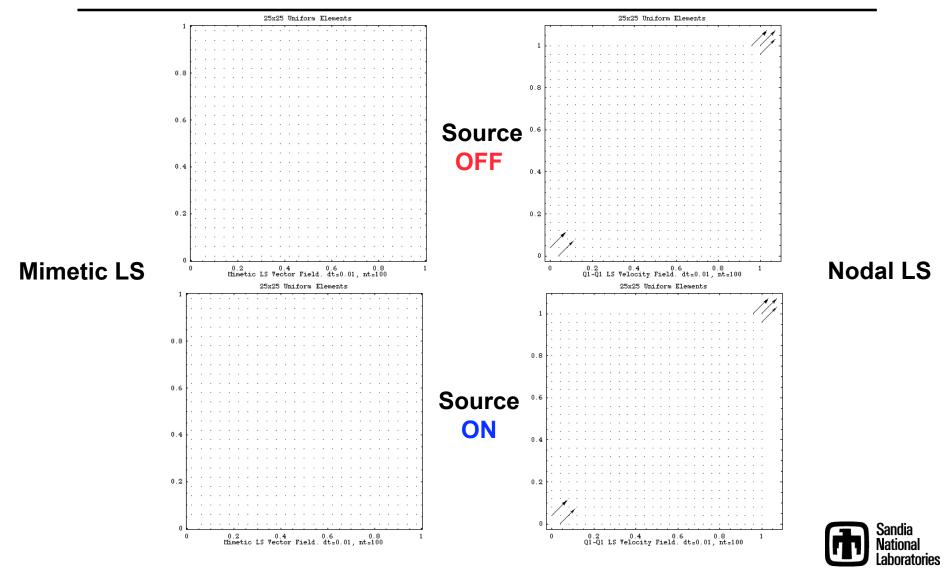
 $f = n\cos(\pi(n-1)x)\cos(\pi(n-1)y) \approx \frac{1}{\pi}\sqrt{\frac{\lambda}{2}}\varphi_{n,n}; \quad n = 25$ 

added perturbation  $\approx \frac{1}{2\pi^2 n} |\varphi_{n,n}| \le 0.002$ 



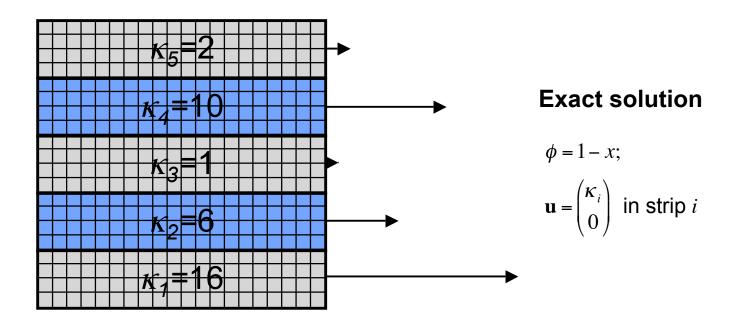


# **Vector Field Comparison**



# **Diffusion: The 5 Strip Problem**

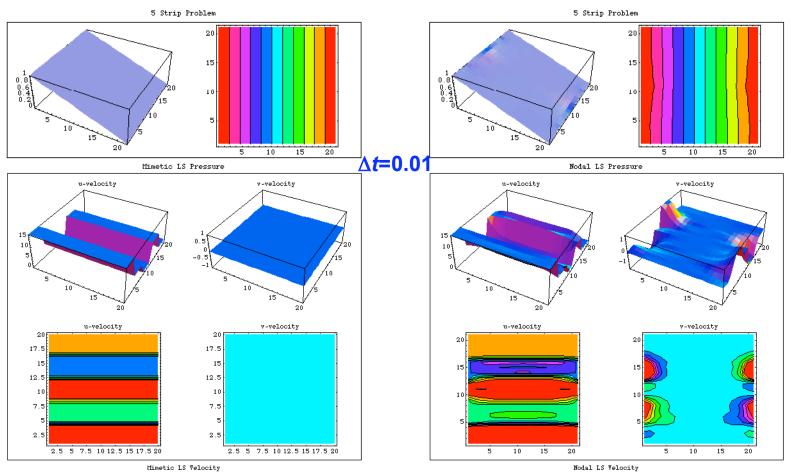
From: T. Hughes, A. Masud and J. Wan, A stabilized mixed DG method for Darcy flow



- Problem is driven by Neumann boundary condition (normal flux)
- ➤ Solved as a time-dependent problem (heat equation) using Implicit Euler
- > Grid has 400 uniform elements aligned with the interfaces between the strips

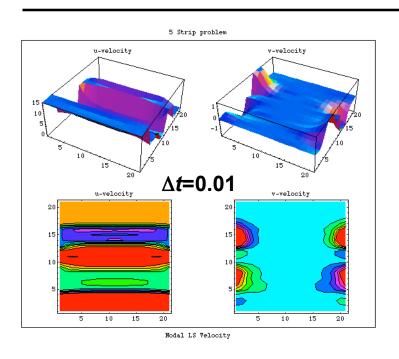


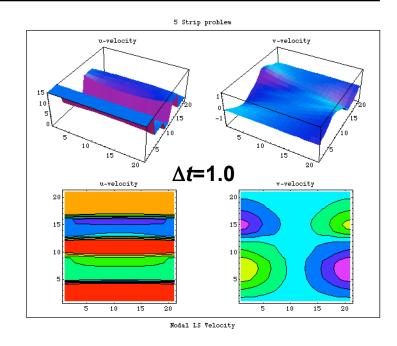
# Mimetic vs. Nodal Least Squares



	L2 Flux	H(div) Flux	L2 Scalar	H1 Scalar
Mimetic LS	0.1670E-08	0.9839E-13	0.4553E-11	0.3041E-13
Nodal LS	0.1759E+01	0.7470E+02	0.8926E-02	0.1425E+00

### **Nodal LS at different time steps**





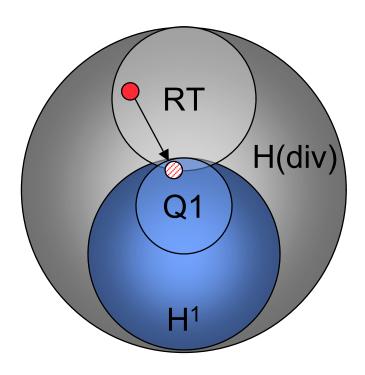
Nodal LS Solution worsens when  $\Delta t$  is reduced

	L2 Flux	H(div) Flux	L2 Scalar	H1 Scalar
Δ <i>t</i> =1.0	0.1925E+01	0.7206E+02	0.8892E-02	0.1423E+00
∆ <i>t</i> =0.01	0.1759E+01	0.7470E+02	0.8926E-02	0.1425E+00



### Why Nodal LS fails?

Solution of the 5 strip problem belongs to the discrete space: recovered by the mimetic LS



Least-Squares solution is a projection onto the discrete space

gives the best possible approximation out of that space with respect to the energy norm

Nodal Least-Squares: gives the best energy norm approximation of that solution out of Q1





## **Conclusions (I)**

**Mimetic Least-Squares** (MLS) for 2nd order PDEs result from **weakly enforced** material laws and provide **realization** of a discrete Hodge \* operator

**MLS** offer important advantages:

- ✓ discrete spaces not subject to a joint inf-sup: can be selected independently!
- ✓ MLS inherit the best computational properties of primal and dual mimetic:
  - **Primal** → Optimal accuracy in the **primal** variable
  - **Dual** → Optimal accuracy in the **dual** variable
- ✓ MLS are locally conservative
- ✓ MLS lead to symmetric and positive definite algebraic systems

Mimetic least-squares are an attractive alternative to mixed and finite volume schemes





## **Conclusions (II)**

There's no free lunch: least-squares are not **immune** to compatibility:



LS allow to circumvent compatibility between the spaces



LS do not allow to circumvent compatibility of spaces

The latter is governed by **PDE structure** and must be respected!

#### References

- 1. P. Bochev and M. Hyman, *Principles of mimetic discretiations*, **Proc. IMA Workshop on Compatible discretizations**, Springer Verlag, To appear 2006.
- 2. P. Bochev, A discourse on variational and geometric aspects of stability of discretizations. In: 33rd Computational Fluid Dynamics Lecture Series, VKI LS 2003, Von Karman Institute for Fluid Dynamics
- 3. P. Bochev and M. Gunzburger, Locally conservative least-squares methods for the Darcy flow, CMAME, submitted
- 4. P. Bochev and P. Gunzburger, *Compatible discretizations of second order elliptic problems*, **Notices of the Steklov Institute**, St. Petersburgh branch, 2005
- 5. P. Bochev and M. Gunzburger, On least-squares finite element methods for the Poisson equation and their connection to the Dirichlet and Kelvin principles. **SIAM J. Num. Anal.**, Vol. 43/1, pp. 340-362, 2005

#### Related work

- 1. I. Perugia, A field-based mixed formulation for the 2D magnetostatics problem, **SINUM** 34, 1997
- 2. F. Brezzi, et al, A novel field-based mixed formulation of magnetostatics IEEE MAG-32, 1996
- 3. A. Bossavit, A rationale for edge elements in 3D fields computations, IEEE MAG-24, 1988



### Magnetic Diffusion: Z-Pinch Model

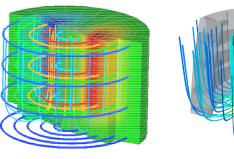
#### Scales:

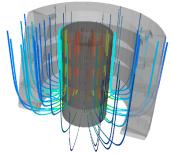
PULSE DURATION 10<sup>-9</sup> sec
TIME SCALE 10<sup>-3</sup> sec
CURRENT POWER 20x10<sup>6</sup> A

X-RAY POWER 10<sup>12</sup> W

X-RAY ENERGY 1.9x10<sup>6</sup> J

C. Garasi, A. Robinson

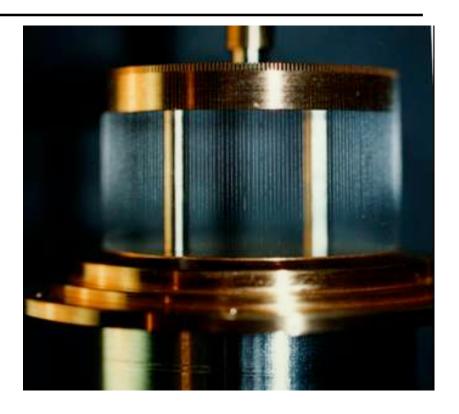




MHD MODEL

=

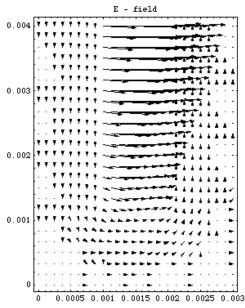
Hydrodynamics + Magnetic Diffusion

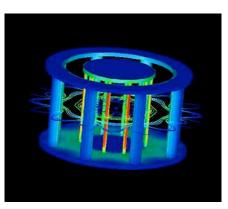


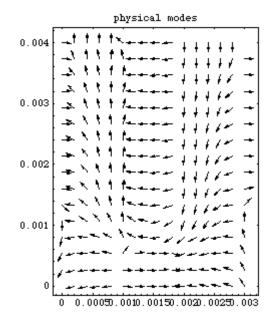
**Z-machine:** Electric currents are used to produce an ionized gas by vaporizing a spool-of-thread sized array of 100-400 wires of diameter ≈ 10µm

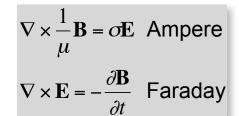


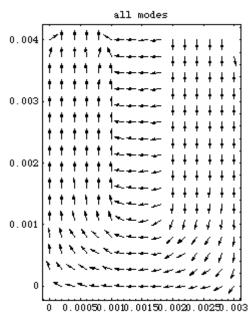
#### Mimetic LS vs. Nodal LS: E-field











Gap modeled as a heterogeneous conductor



### Mimetic LS vs. Nodal LS: B-field

